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QUFINITE

*Zx-calculus*

A UNIFIED FRAMEWORK OF  
QUDIT ZX-CALCULI

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# Qufinite ZX-calculus: a unified framework of qudit ZX-calculi

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## Abstract

ZX-calculus is graphical language for quantum computing which usually focuses on qubits. In this paper, we generalise qubit ZX-calculus to qudit ZX-calculus in any finite dimension by introducing suitable generators, especially a carefully chosen triangle node. As a consequence we obtain a set of rewriting rules which can be seen as a direct generalisation of qubit rules, and a normal form for any qudit vectors. Based on the qudit ZX-calculi, we propose a graphical formalism called qufinite ZX-calculus as a unified framework for all qudit ZX-calculi, which is universal for finite quantum theory due to a normal form for matrix of any finite size. As a result, it would be interesting to give a fine-grained version of the diagrammatic reconstruction of finite quantum theory [12] within the framework of qufinite ZX-calculus.

## 1 Introduction

ZX-calculus is invented as a graphical language for quantum computing [3], so no wonder it is overwhelmingly concentrated on qubits, i.e., each of its wire in a diagram represents a 2-dimensional system and each diagram corresponds to a matrix of size  $2^m \times 2^n$ . Mathematically speaking, ZX-calculus is based on a compact closed PROP [1] represented by Z spiders and X spiders (depicted in green and red respectively in this paper) as main generators as well as rewriting rules which are equalities of diagrams composed vertically or horizontally in terms of those generators. The ZX-calculus is called universal if each matrix of  $2^m \times 2^n$  can be represented by a ZX diagram [3], and is called complete if any two diagrams corresponding to the same matrix can be rewritten into each other with ZX rules [6, 8].

However, qubits are not the whole story. In fact, many quantum systems naturally exhibit more than two dimensions [4], so it would be very useful to have ZX-calculus for higher dimensional quantum systems, i.e., qudits of dimension  $d \geq 2$ . Actually, ZX-calculus has been partly generalised to any finite dimension in [11], and was even more proved to be universal in [17]. But that proof of universality is not a constructive one, which means given a matrix it is not easy in general to construct its corresponding diagram, although in principle this can be done. Furthermore, from the preliminary version of qudit ZX-calculus it is non-trivial to find a way that could lead to a proof of completeness.

On the other hand, qubit ZX-calculus has been proved to be complete via a translation from another graphical calculus called ZW-calculus which is already complete [6, 8]. Although there exists a qudit version of ZW-calculus which is universal due to a normal form [5], it is unclear how completeness for qudit ZW-calculus could be achieved, thus makes it unfeasible to obtain completeness of qudit ZX-calculus by the translation method.

Furthermore, each wire of a qudit ZX diagram represents a  $d$ -dimensional system, while in finite dimensional quantum theory it is quite common that the involved systems have hybrid dimensions instead of some power of  $d$ . Therefore, it is desirable to have a unified framework for qudit ZX-calculi in all finite dimensions.

In this paper, we first generalise qubit ZX-calculus to qudit ZX-calculus in any dimension  $d \geq 2$ . The generators we give here are different from the previous ones [11] in that the Z spider has a phase vector composed of complex numbers rather than real numbers, the generalised Hadamard node and its adjoint are unnormalised, and a generalised triangle node (in comparing to the one given in [7, 6]) and its inverse are added in. As a consequence, the X spider is also unnormalised, and most of the qubit rewriting rules as given in [14] are generalised to the qudit case for any dimension. Note that some of these qudit rewriting rules have been presented in [9] and [13]. Most importantly, the normal form for qubit vectors [14] has been generalised for qudit vectors, which means universality of qudit ZX-calculus and a feasible approach for proof of completeness (similar to the method for qubit ZX shown in [14]).

Then we propose a formalism called qufinite ZX-calculus as a unified framework for qudit ZX-calculi in all finite dimensions. The key idea is to label each wire with its dimension and add two new generators called dimension-splitter and dimension-binder respectively. This formalism is not a PROP anymore, but still a compact closed category. With the new generators and a normal form for qudits, we construct a normal form for arbitrary matrix of size  $m \times n$ . Therefore, the qufinite ZX-calculus is universal for finite dimensional quantum theory.

Finally we mention that the generators (except for the Hadamard node and its adjoint) and the normal form of the qufinite ZX-calculus can be generalised to be over arbitrary commutative semirings. Hence we can have a qufinite ZX-calculus over commutative semirings which is universal and possibly can be proved to be complete following the method given in [15].

## 2 Generators and rules of qudit ZX-calculus

In this paper,  $d$  is an integer and  $d \geq 2$ ,  $\mathbb{C}$  is the field of complex numbers. All the diagrams are read from top to bottom. Similar to the qubit case, qudit ZX-calculus is based on a PROP which can be represented by generators and rewriting rules.

First we give the generators of qudit ZX-calculus.

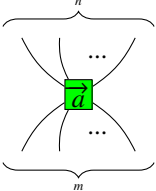








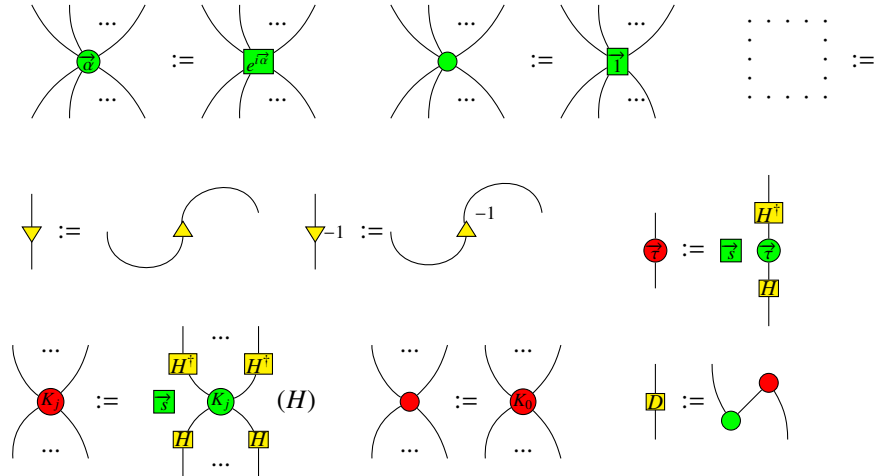
$R_{Z, \vec{a}}^{(n,m)} : n \rightarrow m$		
$H : 1 \rightarrow 1$		$H^\dagger : 1 \rightarrow 1$ 
$\mathbb{I} : 1 \rightarrow 1$		$\sigma : 2 \rightarrow 2$ 
$C_a : 0 \rightarrow 2$		$C_u : 2 \rightarrow 0$ 
$T_g : 1 \rightarrow 1$		$T_g^{-1} : 1 \rightarrow 1$ 

Table 1: Generators of qudit ZX-calculus, where  $m, n \in \mathbb{N}$ ,  $\vec{a} = (a_1, \dots, a_{d-1})$ ,  $a_i \in \mathbb{C}$ .

For convenience, we make the following denotations:



where  $\vec{\alpha} = (\alpha_1, \dots, \alpha_{d-1})$ ,  $\alpha_i \in \mathbb{R}$ ,  $e^{i\vec{\alpha}} = (e^{i\alpha_1}, \dots, e^{i\alpha_{d-1}})$ ,  $\vec{1} = \overbrace{(1, \dots, 1)}^{d-1}$ ,  $\vec{s} = (0, \dots, 0, \frac{1}{d} - 1)$ ,  $\vec{\tau} = (\tau_1, \dots, \tau_k, \dots, \tau_{d-1})$ ,  $\tau_k = k\pi + \frac{k^2\pi}{d}$ ,  $1 \leq k \leq d-1$ ,  $K_j = (j\frac{2\pi}{d}, 2j\frac{2\pi}{d}, \dots, (d-1)j\frac{2\pi}{d})$ ,  $0 \leq j \leq d-1$ .

The diagrams of the qudit ZX-calculus have the following standard interpretation  $[\![ \cdot ]\!]$ :

$$\left[ \begin{array}{c} \overbrace{\left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right]}^n \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \underbrace{\hspace{1.5cm}}_m \end{array} \right] = \sum_{j=0}^{d-1} a_j |j\rangle^{\otimes m} \langle j|^{\otimes n}, a_0 = 1, \vec{a} = (a_1, \dots, a_{d-1}), a_i \in \mathbb{C}.$$

$$\left[ \begin{array}{c} \overbrace{\left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right]}^n \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \underbrace{\hspace{1.5cm}}_m \end{array} \right] = \sum_{\substack{0 \leq i_1, \dots, i_m, j_1, \dots, j_n \leq d-1 \\ i_1 + \dots + i_m + j \equiv j_1 + \dots + j_n \pmod{d}}} |i_1, \dots, i_m\rangle \langle j_1, \dots, j_n|, \quad K_j = (j \frac{2\pi}{d}, 2j \frac{2\pi}{d}, \dots, (d-1)j \frac{2\pi}{d}), 0 \leq j \leq d-1,$$

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \sum_{k,j=0}^{d-1} \xi^{jk} |j\rangle \langle k|, \xi = e^{i \frac{2\pi}{d}}, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \sum_{k,j=0}^{d-1} \bar{\xi}^{jk} |j\rangle \langle k|, \bar{\xi} = e^{-i \frac{2\pi}{d}},$$

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = I_d + \sum_{i=1}^{d-1} |0\rangle \langle i|, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right]^{-1} \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = I_d - \sum_{i=1}^{d-1} |0\rangle \langle i|,$$

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \frac{1}{d} \sum_{k,l,n=0}^{d-1} e^{i\tau_l} \xi^{(k-n)l} |k\rangle \langle n|, \vec{\tau} = (\tau_1, \dots, \tau_k, \dots, \tau_{d-1}), \tau_k = k\pi + \frac{k^2\pi}{d}, 0 \leq k \leq d-1,$$

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = I_d = \sum_{j=0}^{d-1} |j\rangle \langle j|, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \sum_{i,j=0}^{d-1} |ji\rangle \langle ij|, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \sum_{j=0}^{d-1} |jj\rangle, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \sum_{j=0}^{d-1} \langle jj|, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = 1,$$

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \otimes \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \otimes \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \otimes \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \otimes \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right], \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \circ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \circ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \circ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \circ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right].$$

In particular,

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = |d-j\rangle, \quad \left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \langle j|, 0 \leq j \leq d-1 (|0\rangle = |d\rangle).$$

**Remark 2.1** The interpretation of the  $H$  node is the usual quantum Fourier transform without the scalar  $\frac{1}{\sqrt{d}}$  [10], and the  $H^\dagger$  node is the unnormalised inverse quantum Fourier transform. Also note that  $\tau_{d-k} \equiv \tau_k \pmod{2\pi}$ , i.e.,  $\vec{\tau} = \overleftarrow{\tau}$ .

In the qubit case, the triangle node has the following interpretation:

$$\left[ \begin{array}{c} \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \\ \left[ \begin{array}{c} \vdots \\ \vdots \\ \vdots \end{array} \right] \end{array} \right] = \begin{pmatrix} 1 & 1 \\ 0 & 1 \end{pmatrix}$$

When generalising the triangle node to higher dimensional cases, there could be multiple choices. Here we adopt the following form which turns out to be very useful:

$$\left[ \begin{array}{c} \text{triangle} \\ \text{---} \\ \text{---} \\ \text{---} \\ \text{---} \end{array} \right] = \begin{pmatrix} 1 & 1 & \cdots & 1 \\ & 1 & \cdots & 0 \\ & & \ddots & \vdots \\ & & & 1 \end{pmatrix}$$

where the elements of the first row and the diagonal are 1 and the entries in other places are just 0.

**Remark 2.2** As once can see from the standard interpretation of the diagrams, if we add in the red spiders labelled with  $K_j$  while drop off the  $H$  node and the  $H^\dagger$  node from the Table 2 of the qudit generators, then we get the generators of qudit ZX-calculus over arbitrary commutative semirings in any finite dimension, as have been shown in [13].

Below we show some rules of qudit ZX-calculus in any dimension  $d \geq 2$  which are directly generalised from the rules for qubits [14].

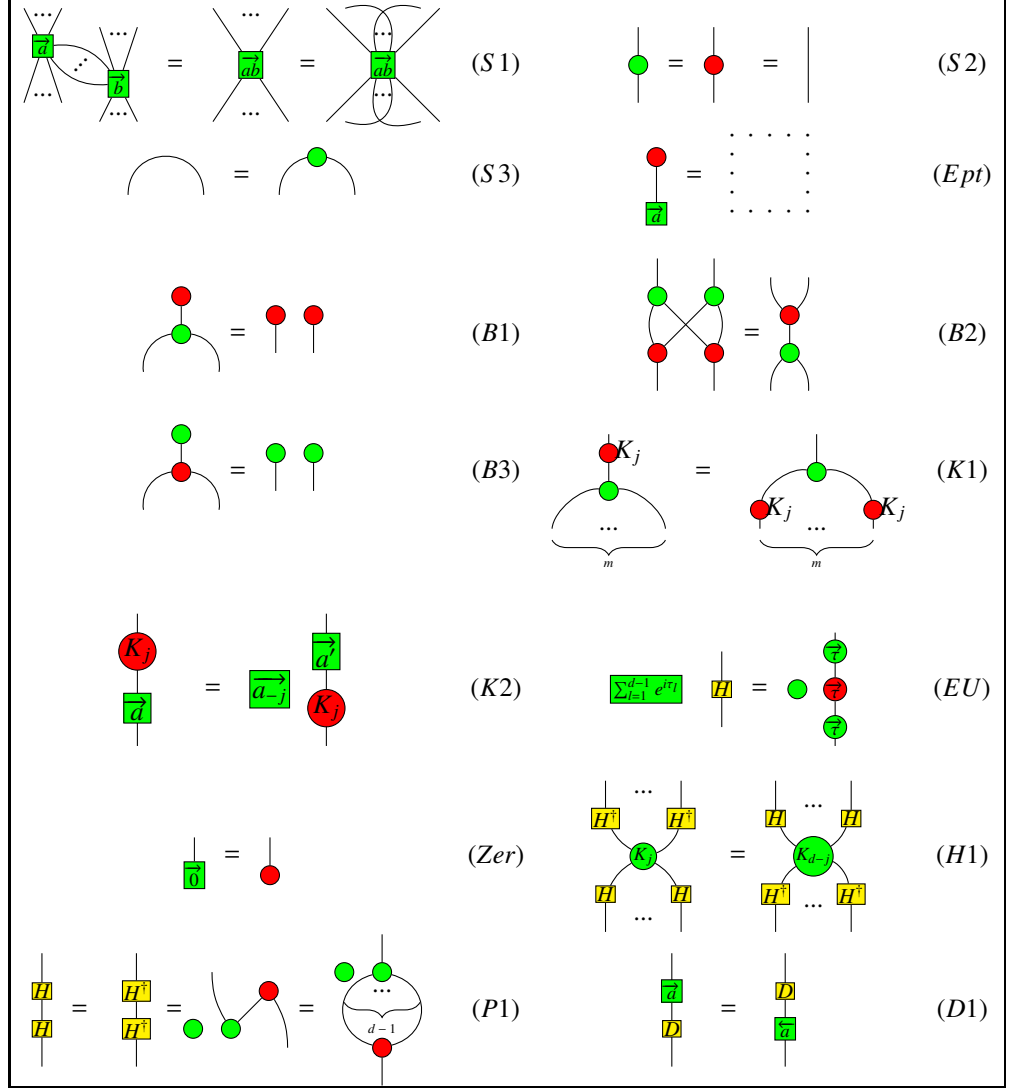


Figure 1: Qudit ZX-calculus rules I, where  $\vec{a} = (a_1, \dots, a_{d-1})$ ,  $\overleftarrow{a} = (a_{d-1}, \dots, a_1)$ ,  $\vec{a}' = (\frac{a_1-j}{a_{d-j}}, \dots, \frac{a_{d-1-j}}{a_{d-j}})$ ,  $\vec{a}_{-j} = (0, \dots, 0, a_{d-j} - 1)$ ,  $j \in \{0, 1, \dots, d-1\}$ ,  $a_0 = a_d = 1$ ,  $\vec{b} = (b_1, \dots, b_{d-1})$ ,  $\vec{a}\vec{b} = (a_1b_1, \dots, a_{d-1}b_{d-1})$ ,  $a_k, b_k \in \mathbb{C}$ ,  $k \in \{1, \dots, d-1\}$ ,  $m \in \mathbb{N}$ ,  $\vec{\tau} = (\tau_1, \dots, \tau_k, \dots, \tau_{d-1})$ ,  $\tau_k = k\pi + \frac{k^2\pi}{d}$ ,  $0 \leq k \leq d-1$ ;  $K_j = (j\frac{2\pi}{d}, 2j\frac{2\pi}{d}, \dots, (d-1)j\frac{2\pi}{d})$ ,  $0 \leq j \leq d-1$ ,  $\vec{0} = \overbrace{(0, \dots, 0)}^{d-1}$ . We assume that all the upside-down flipped version of these rules still hold.

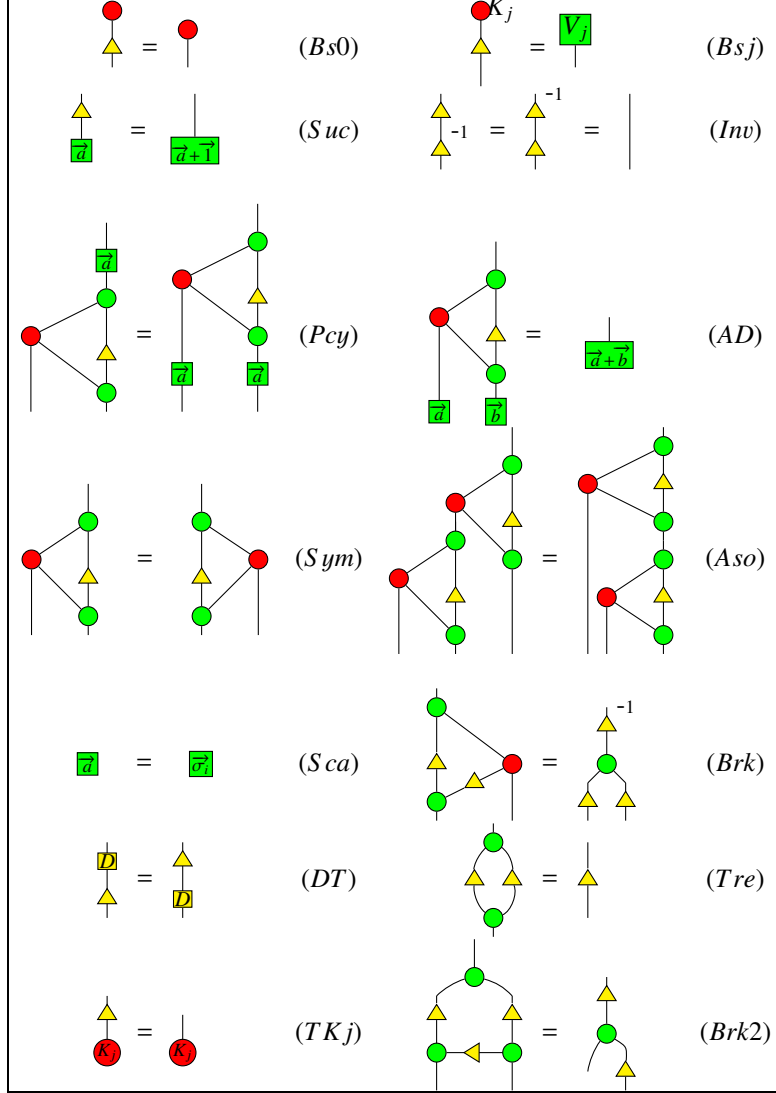


Figure 2: Qudit ZX-calculus rules II, where  $\vec{1} = \overbrace{(1, \dots, 1)}^{d-1}$ ;  $\vec{a} = (a_1, \dots, a_{d-1})$ ;  $\vec{b} = (b_1, \dots, b_{d-1})$ ;  $a_k, b_k \in \mathbb{C}, k \in \{1, \dots, d-1\}$ ;  $\vec{\sigma}_i = \underbrace{(0, \dots, 0, \sum_{k=1}^{d-1} a_k, \dots, 0)}_i$ ,  $i \in \{1, \dots, d-1\}$ ;  $V_j = \underbrace{(0, \dots, 1, \dots, 0)}_{d-j}$ ;  $j \in \{1, \dots, d-1\}$ .

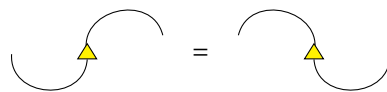


**Remark 2.3** The rule (EU) given in Figure 1 was essentially found (without scalars) by KangFeng Ng and the author as a generalisation of the Euler decomposition of the Hadamard gate. This rule has been reported in several talks, e.g., in QPL 2019 [9].

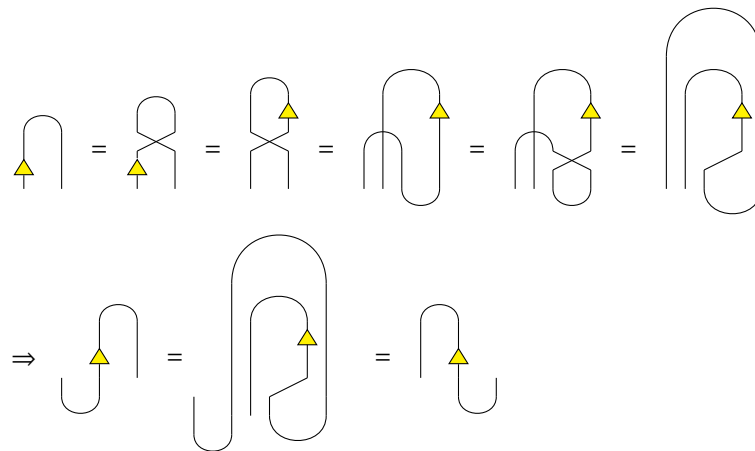
### 3 Properties of qudit ZX-calculus

In this section, we show that given the above generators and rewriting rules of qudit ZX-calculus, what kind of properties it would have. These properties will be presented in terms of lemmas, corollaries and propositions.

First, we show that why the transpose of the triangle node is well-defined.

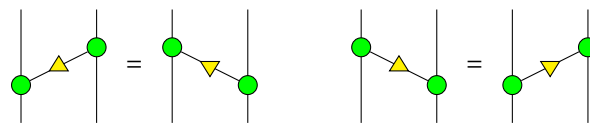
**Lemma 3.1** 

**Proof:**

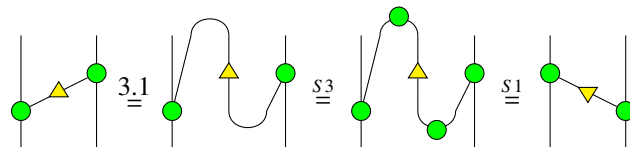


□

**Lemma 3.2**



**Proof:**



The second equality can be proved similarly. □  
 This lemma justifies the usage of a triangle node on a horizontal wire as used in rule (Brk2).

**Lemma 3.3**

$$\begin{array}{c} \textcircled{K} \\ \boxed{d} \end{array} = \begin{array}{c} \square \\ (0, \dots, a_{d-j-1}, \dots, 0) \\ \substack{1 \\ d-j \\ d-1} \end{array}$$

where  $\vec{a} = (a_1, \dots, a_{d-1})$ ,  $j \in \{1, \dots, d-1\}$ .

**Proof:**

$$\begin{array}{c} \textcircled{K} \\ \boxed{d} \end{array} \stackrel{Suc}{=} \begin{array}{c} \textcircled{K} \\ \triangle \\ \boxed{d-1} \end{array} \stackrel{Bsj}{=} \begin{array}{c} \boxed{V} \\ \boxed{d-1} \end{array} \stackrel{S1}{=} \begin{array}{c} \square \\ (0, \dots, a_{d-j-1}, \dots, 0) \\ \substack{1 \\ d-j \\ d-1} \end{array}$$

□

**Lemma 3.4**  $\begin{array}{c} \square \\ \boxed{0} \end{array} = \begin{array}{c} \dots \\ \dots \\ \dots \end{array}$

**Proof:**

$$\begin{array}{c} \square \\ \boxed{0} \end{array} \stackrel{S1}{=} \begin{array}{c} \boxed{0} \\ \boxed{0} \end{array} \stackrel{Zer}{=} \begin{array}{c} \textcircled{K} \\ \boxed{0} \end{array} \stackrel{Ept}{=} \begin{array}{c} \dots \\ \dots \\ \dots \end{array}$$

□

**Lemma 3.5**

$$\begin{array}{c} \bullet \\ \boxed{s} \end{array} = \begin{array}{c} \dots \\ \dots \\ \dots \end{array}$$

where  $\vec{s} = (0, \dots, 0, \frac{1}{d} - 1)$ .

**Proof:**

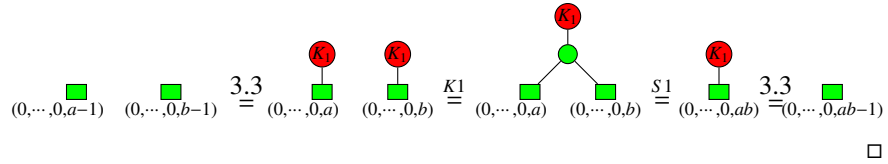
$$\begin{array}{c} \bullet \\ \boxed{s} \end{array} \stackrel{Sca}{=} \begin{array}{c} \square \\ (0, \dots, 0, d-1) \end{array} \stackrel{3.3}{=} \begin{array}{c} \textcircled{K} \\ \square \\ (0, \dots, 0, d) \end{array} \stackrel{K1}{=} \begin{array}{c} \textcircled{K} \\ \square \\ (0, \dots, 0, \frac{1}{d}) \end{array} \stackrel{S1}{=} \begin{array}{c} \textcircled{K} \\ \square \\ (0, \dots, 0, 1) \end{array} \stackrel{3.3}{=} \begin{array}{c} \square \\ \boxed{0} \end{array} \stackrel{3.4}{=} \begin{array}{c} \dots \\ \dots \\ \dots \end{array}$$

□

**Lemma 3.6**

$$\begin{array}{|c} \square \\ \hline (0, \dots, 0, a-1) \end{array} \begin{array}{|c} \square \\ \hline (0, \dots, 0, b-1) \end{array} = \begin{array}{|c} \square \\ \hline (0, \dots, 0, ab-1) \end{array}$$

**Proof:**



□

**Corollary 3.7**

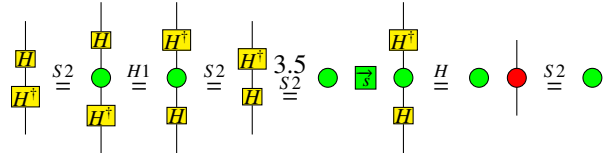
$$\begin{array}{|c} D \\ \hline \end{array} = \begin{array}{|c} \square \\ \hline \end{array} \begin{array}{|c} H \\ \hline \end{array} = \begin{array}{|c} \square \\ \hline \end{array} \begin{array}{|c} H^i \\ \hline \end{array}$$

where  $\vec{s} = (0, \dots, 0, \frac{1}{d} - 1)$ .

This follows directly from lemma 3.5 and the definition of the D box.

**Lemma 3.8**  $\begin{array}{|c} H \\ \hline \end{array} \begin{array}{|c} H^i \\ \hline \end{array} = \begin{array}{|c} H^i \\ \hline \end{array} \begin{array}{|c} H \\ \hline \end{array} = \begin{array}{|c} \bullet \\ \hline \end{array}$

**Proof:**



□

**Corollary 3.9**

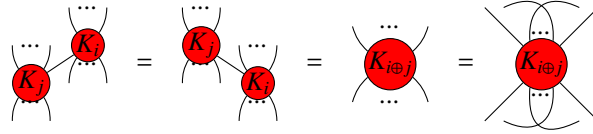
$$\begin{array}{|c} \dots \\ \hline \bullet \\ \hline \dots \\ \hline \end{array} = \begin{array}{|c} \dots \\ \hline \square \\ \hline \dots \\ \hline \end{array} \begin{array}{|c} \dots \\ \hline \bullet \\ \hline \dots \\ \hline \end{array} = \begin{array}{|c} \dots \\ \hline \square \\ \hline \dots \\ \hline \end{array} \begin{array}{|c} \dots \\ \hline \bullet \\ \hline \dots \\ \hline \end{array} \quad (H)$$

where  $\vec{t} = (0, \dots, 0, \frac{1}{d^{m+n-1}} - 1), j \in \{0, 1, \dots, d-1\}$ .

This follows directly from lemma 3.5, (H1) and the definition of the red spider, we also denote the equality as (H).

The X spider fusion rule can also be derived.

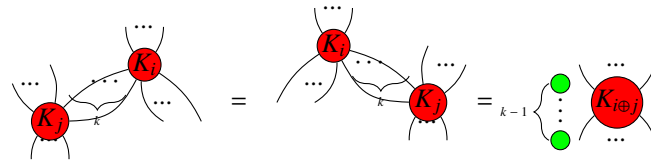
**Lemma 3.10**



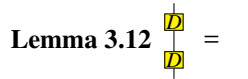
The proof follows directly from (S1), (H) and lemma 3.5 and 3.8.

Note that there is just one edge connected with two X spiders when they are fusing. How about if there are more than one edges appeared?

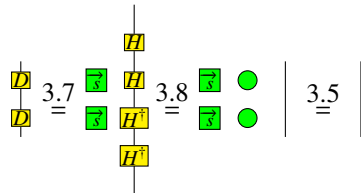
**Lemma 3.11**



The proof is similar to lemma 3.10.



**Proof:**

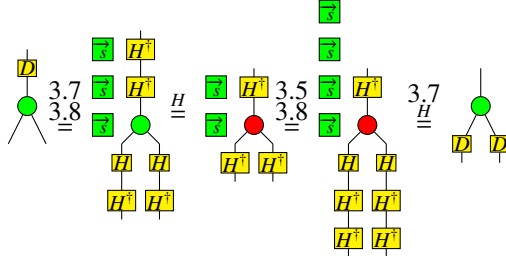


□

**Lemma 3.13**



**Proof:**

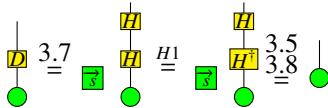


The other equalities can be proved similarly. □

**Lemma 3.14**

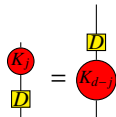


**Proof:**



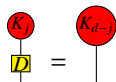
The second equality can be proved similarly. □

**Lemma 3.15**



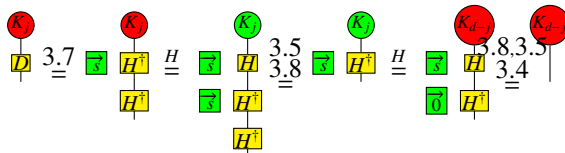
where  $j \in \{0, 1, \dots, d-1\}$ .

**Lemma 3.16**

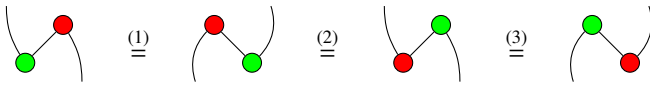


where  $j \in \{0, 1, \dots, d-1\}$ .

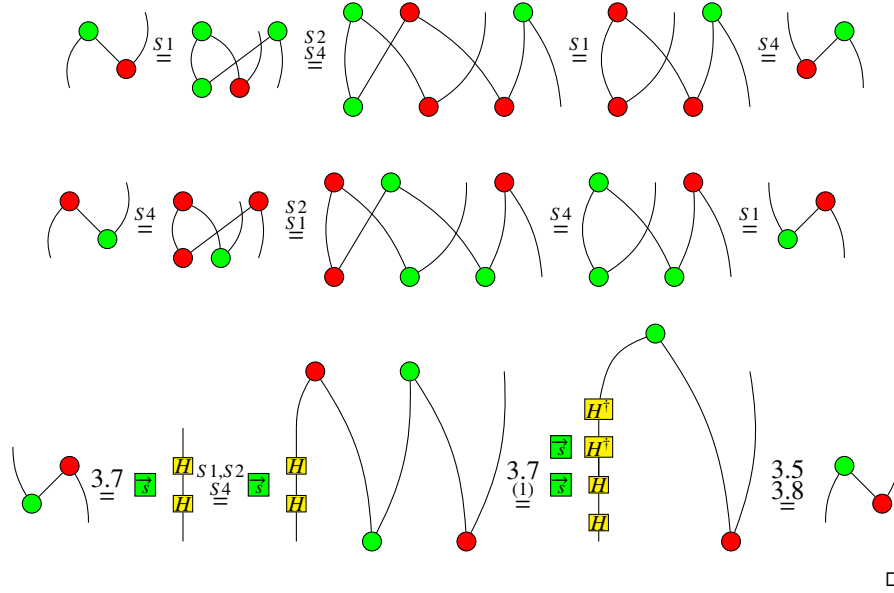
**Proof:**



□

**Lemma 3.17** 

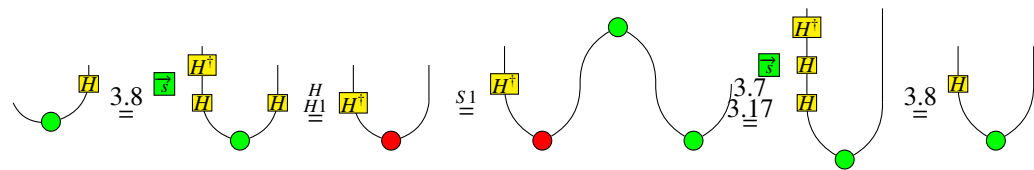
**Proof:**




**Lemma 3.18**



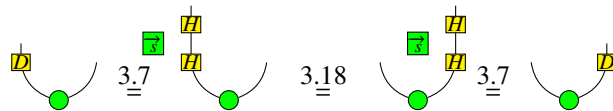
**Proof:**



The other equalities can be proved similarly. □

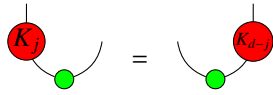
**Corollary 3.19** 

**Proof:**



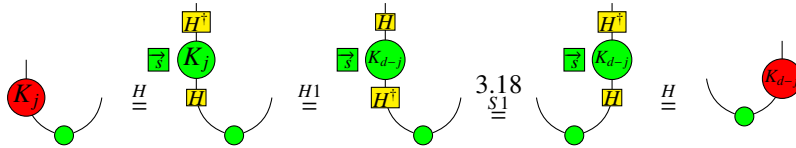
The second equality can be proved similarly. □

**Corollary 3.20**



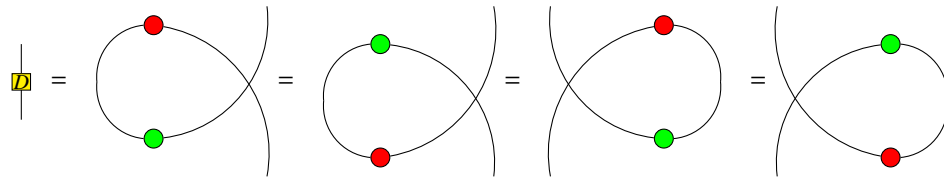
where  $j \in \{0, 1, \dots, d-1\}$ .

**Proof:**

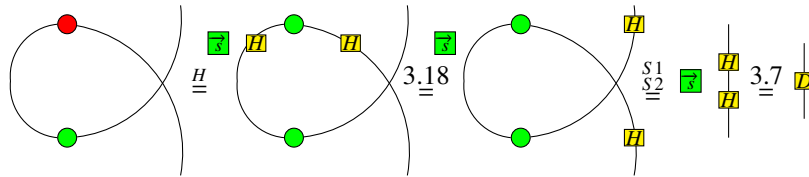


□

**Lemma 3.21**

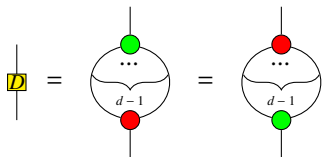


**Proof:** We only prove the first equality, the others can be proved similarly.

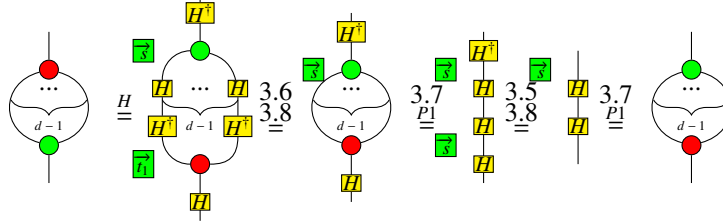


□

**Lemma 3.22**



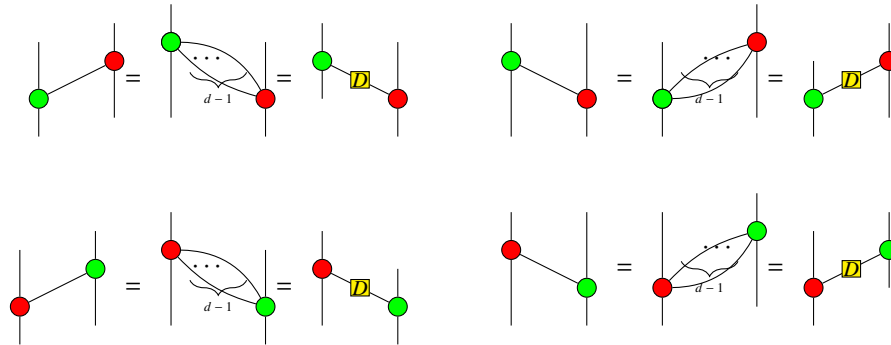
**Proof:**



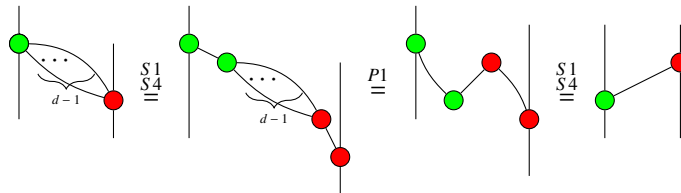
where  $\vec{s} = (0, \dots, 0, \frac{1}{d} - 1)$ ,  $\vec{t}_1 = (0, \dots, 0, \frac{1}{d^{d-1}} - 1)$ . □

Next we show that it doesn't make sense anymore to draw a horizontal line between Z spider and X spider in higher dimensional ZX-calculus ( $d \geq 3$ ), which would be one of the main difference in comparison to qubit ZX-calculus.

**Lemma 3.23**



**Proof:** We only prove the first equality, the others can be proved similarly.

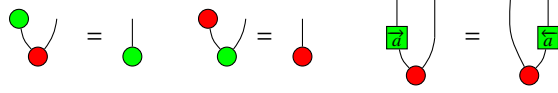


□

**Remark 3.24** With lemma 3.23, now we can use cap ( $C_a$ ) and cup ( $C_u$ ) to transpose simultaneously the diagrams on each side of the rules listed in Figure 2, so that the upside-down flipped version of those rules still hold, except the rule (Bsj) which has the form  $\begin{array}{c} \triangle \\ \text{red circle} \end{array} = \begin{array}{c} \square \\ \text{red circle} \end{array}$  after transpose. We will use the same name for the flipped version of those rules.

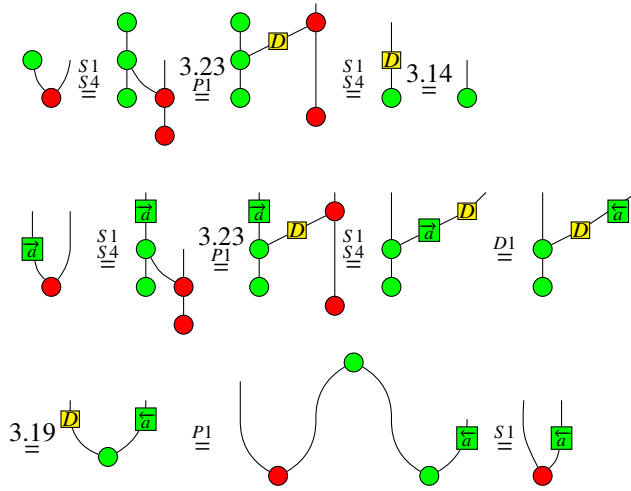


**Lemma 3.25**



where  $\vec{a} = (a_1, \dots, a_{d-1})$ ,  $\overleftarrow{a} = (a_{d-1}, \dots, a_1)$ .

**Proof:**

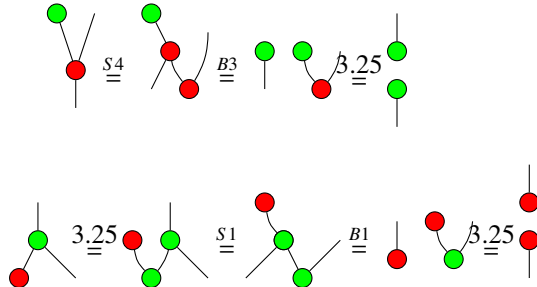


The second equality can be proved similarly as for the first one. □

**Lemma 3.26**

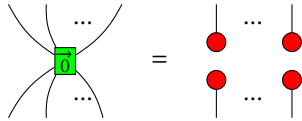


**Proof:**

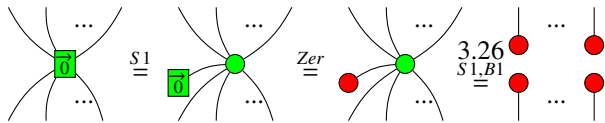


□

**Lemma 3.27**

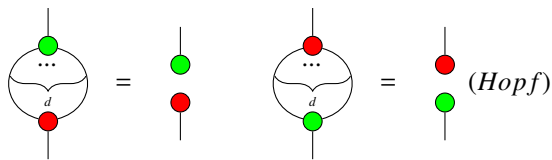


**Proof:**

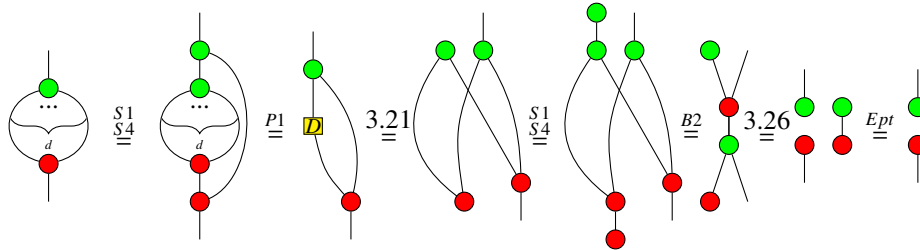


□

**Lemma 3.28**



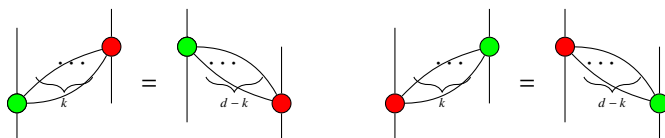
**Proof:**



The second equality can be proved similarly.

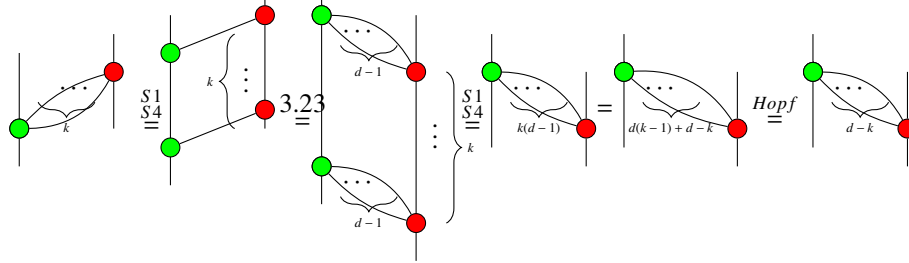
□

**Corollary 3.29**








where  $1 \leq k \leq d-1$ .

**Proof:**



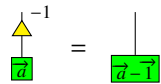
□




**Lemma 3.30**  = 

**Proof:**   $\stackrel{Zer}{\equiv}$    $\stackrel{Suc}{\equiv}$   = 

□

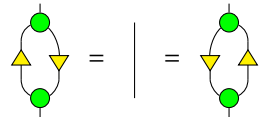
**Lemma 3.31**



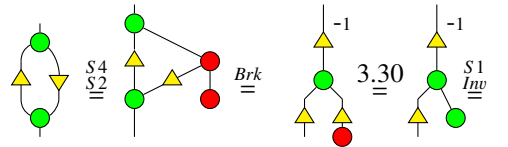
**Proof:**   $\stackrel{Suc}{\equiv}$    $\stackrel{Inv}{\equiv}$  

□

**Lemma 3.32**



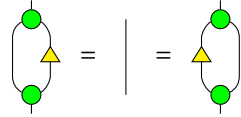
**Proof:**



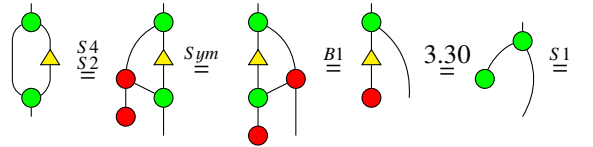
The second equality can be proved similarly.

□

**Lemma 3.33**

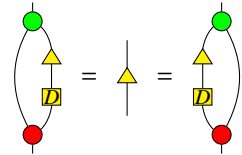


**Proof:**

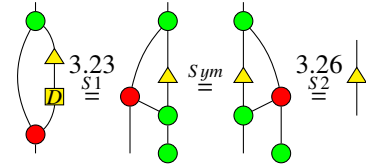


The second equality can be proved similarly. □

**Lemma 3.34**

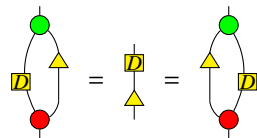


**Proof:**

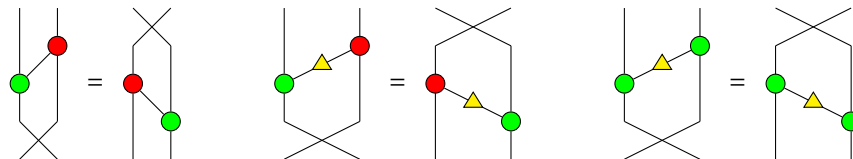


The second equality can be proved similarly. □

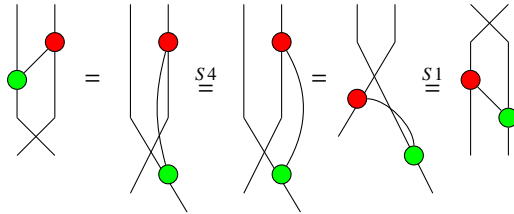
**Corollary 3.35**



**Lemma 3.36**

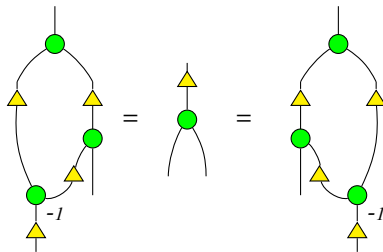


**Proof:**

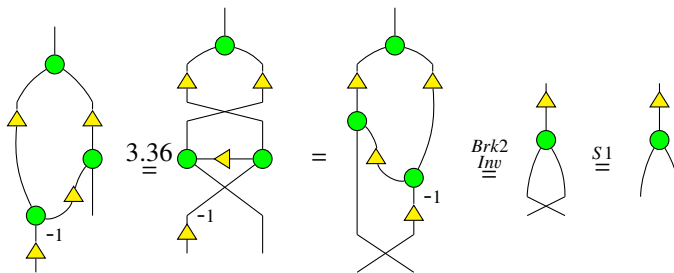


The second and the third equalities can be proved similarly. □

**Lemma 3.37**



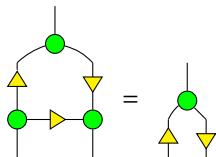
**Proof:** The second equality follows directly from rules (Brk2) and (Inv). We only prove the first equality.



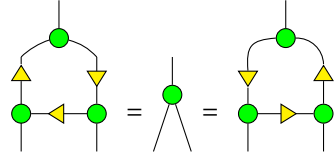
□

If we do partial transpose (bending wires) on both sides of the rule (Brk2), then we get

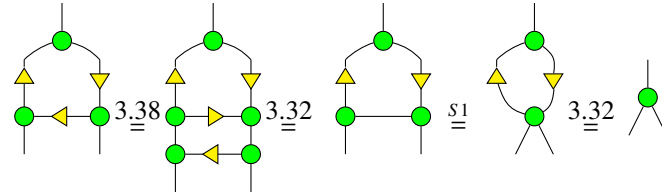
**Lemma 3.38**



**Lemma 3.39**

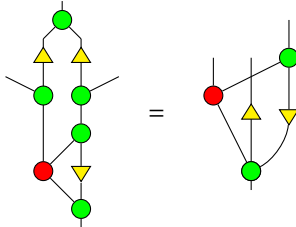


**Proof:**

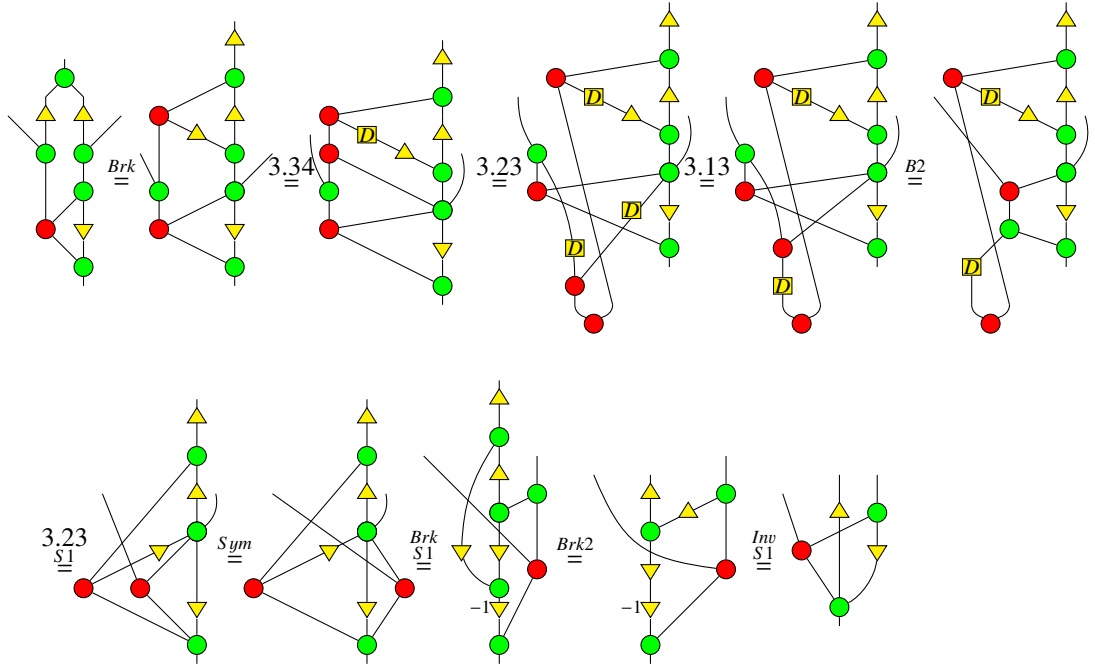


The other part of the equality can be obtained by symmetry. □

**Lemma 3.40**

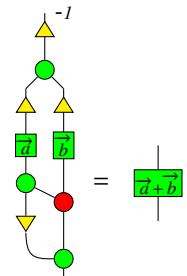


**Proof:**



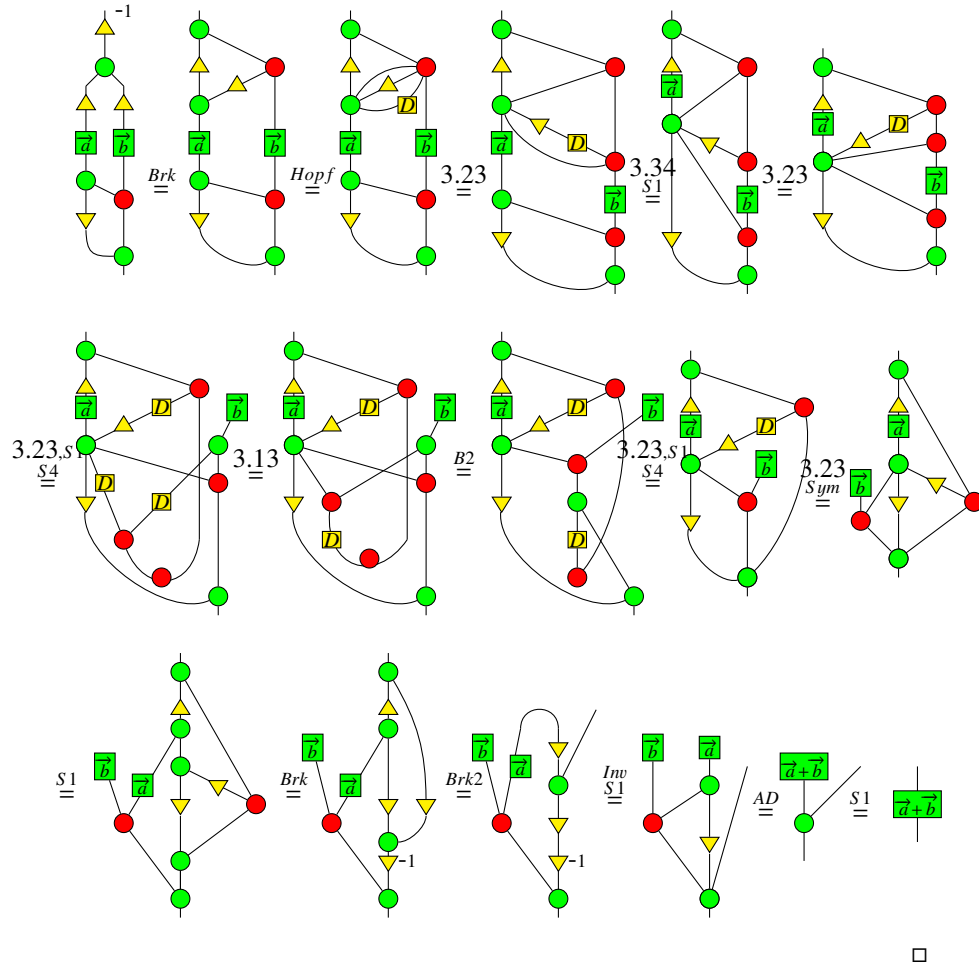
□

**Lemma 3.41** Let  $\vec{a} = (a_1, \dots, a_{d-1})$ ,  $\vec{b} = (b_1, \dots, b_{d-1})$ ,  $a_k, b_k \in \mathbb{C}$ ,  $k \in \{1, \dots, d-1\}$ .

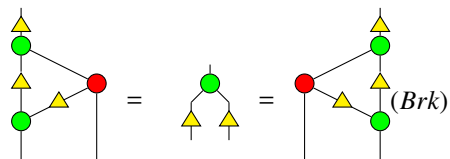


**Proof:** This lemma follows directly from lemma 3.40 and the (AD) rule, here we just

give another proof.

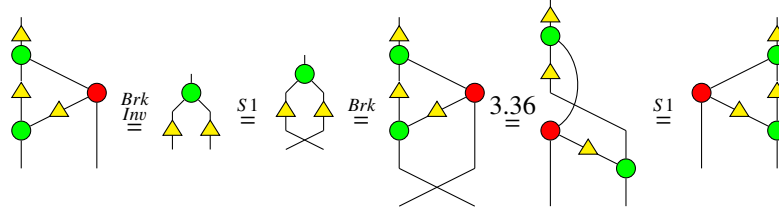


**Lemma 3.42**



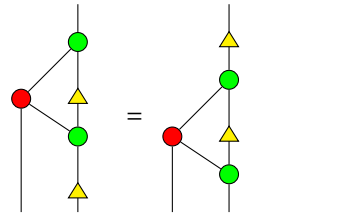


**Proof:**

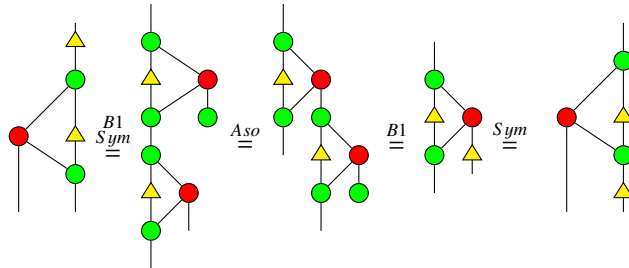


We call this derived equality (Brk) as well, since it is a variant of the (Brk). □

**Lemma 3.43**

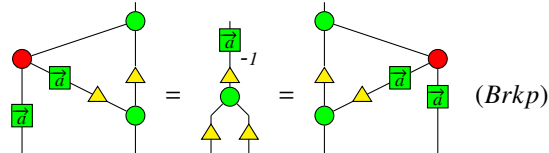


**Proof:**



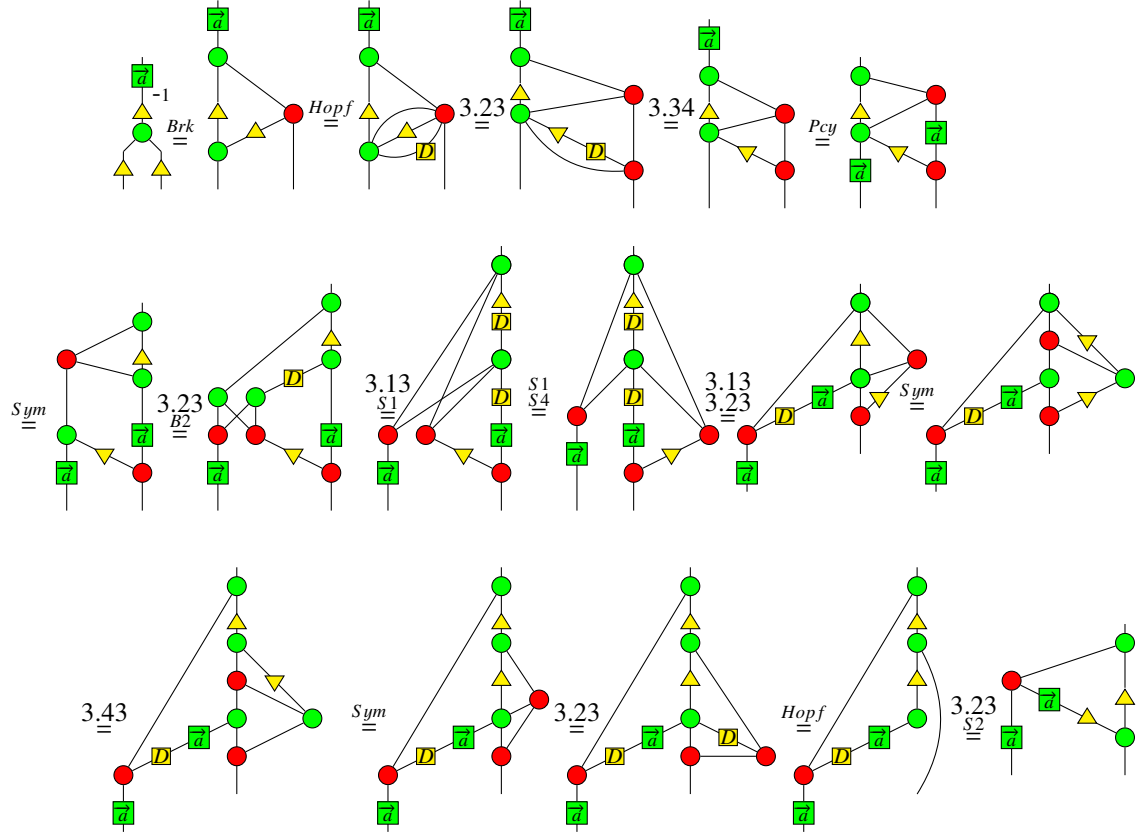
□

**Lemma 3.44**

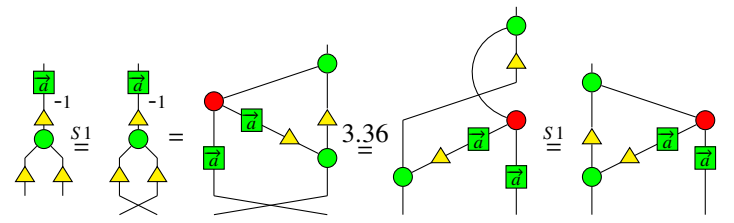


where  $\vec{a} = (a_1, \dots, a_{d-1})$ .

**Proof:**

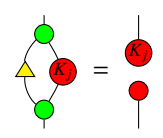


Therefore,

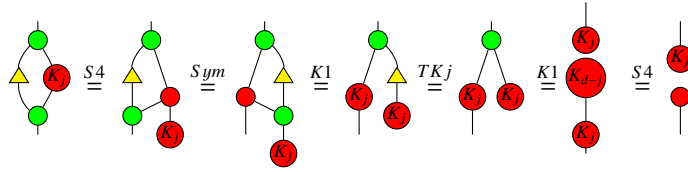


□

**Lemma 3.45** Let  $1 \leq j \leq d - 1$ . Then

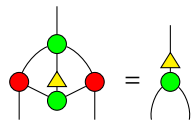


**Proof:**

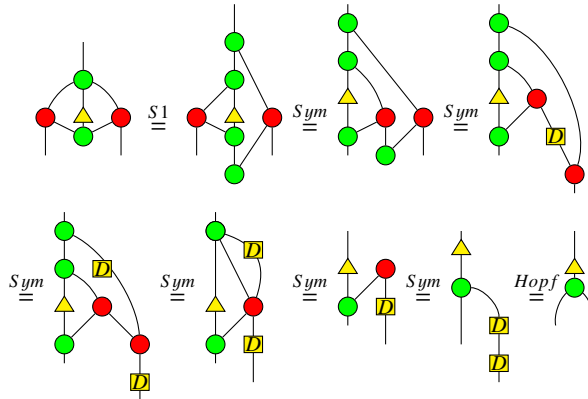


□

**Lemma 3.46**

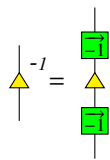


**Proof:**



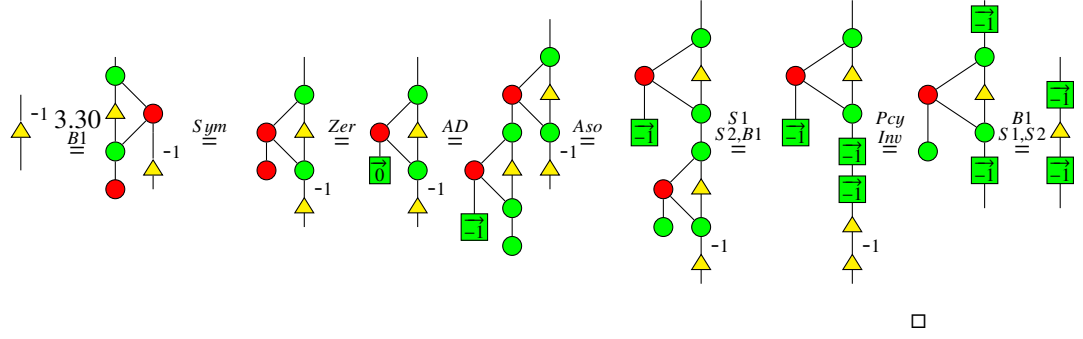
□

**Lemma 3.47**



where  $\vec{-1} = \overbrace{(-1, \dots, -1)}^{d-1}$ .

**Proof:**



□

## 4 Normal form for qudits

Suppose  $\{e_k | 0 \leq k \leq d^m - 1\}$  are the  $d^m$ -dimensional standard unit column vectors (with entries all 0s except for a single 1):

$$e_k = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \begin{matrix} r_0 \\ \vdots \\ r_k \\ \vdots \\ r_{d^m-1} \end{matrix}$$

where  $r_i$  denote the  $i$ -th row,  $0 \leq i \leq d^m - 1, m \geq 1$ .

Let

$$|i\rangle = \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \begin{matrix} r_0 \\ \vdots \\ r_i \\ \vdots \\ r_{d-1} \end{matrix}$$

where  $r_i$  denotes the  $i$ -th row,  $0 \leq i \leq d - 1$ .

Then

### Lemma 4.1

$$|a_{m-1} \cdots a_k \cdots a_0\rangle = e_{\sum_{i=0}^{m-1} a_i d^i}, \tag{1}$$

where  $a_k \in \{0, 1, \dots, d - 1\}, 0 \leq k \leq m - 1, m \geq 1$ .



$\{0, 1, \dots, d-2\}$ . Therefore,

$$\left[ \begin{array}{cccc} \kappa_{i_{m-1}} & \kappa_{i_j} & \kappa_{i_t} & \kappa_{i_0} \\ \vdots & \vdots & \vdots & \vdots \\ m-1 & j & t & 0 \end{array} \right] = e_k$$

where  $i_t \in \{0, 1, \dots, d-1\}$  and  $i_t \neq 1$ . Then for  $0 \leq k \leq d^m - 2$ , we have

$$Ae_k = \left[ \begin{array}{cccccccccccc} \kappa_{i_{m-1}} & \kappa_{i_{j_s}} & \kappa_{i_{j_1}} & \kappa_{i_t} & \kappa_{i_0} & \kappa_{i_{m-1}} & \kappa_{i_{j_s}} & \kappa_{i_{j_1}} & \kappa_{i_t} & \kappa_{i_0} & \dots & \kappa_{i_{m-1}} & \kappa_{i_{j_s}} & \kappa_{i_{j_1}} & \kappa_{i_t} & \kappa_{i_0} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ m-1 & j_s & j_1 & t & 0 & m-1 & j_s & j_1 & t & 0 & \dots & m-1 & j_s & j_1 & t & 0 \end{array} \right] = e_k$$

$S1, Bs0$   
 $Bsj, Zer$   
 $S1, S4$   
 $S1, S4$

For  $k = d^m - 1$ , we have

$$\left[ \begin{array}{ccc} \kappa_1 & \dots & \kappa_1 \\ \vdots & \vdots & \vdots \\ m-1 & j_1 & 0 \end{array} \right] = e_{d^m-1}$$

Then

$$\begin{aligned} Ae_k &= \left[ \begin{array}{cccc} \kappa_1 & \kappa_1 & \kappa_1 & \kappa_1 \\ \vdots & \vdots & \vdots & \vdots \\ m-1 & j_s & j_1 & 0 \end{array} \right] \stackrel{S1, Bs, Zer}{=} \left[ \begin{array}{cccc} \kappa_1 & \dots & \kappa_1 & \dots \\ \vdots & \vdots & \vdots & \vdots \\ m-1 & j_s & j_1 & 0 \end{array} \right] \\ &= [(d-1) \otimes \dots \otimes I_d \otimes \dots \otimes (d-1) \otimes \dots \otimes I_d \otimes \dots \otimes (d-1)] \circ [(d-1)^{\otimes s} + a[(d-1-k_s), \dots, (d-1-k_1)]] \\ &= (d-1)^{\otimes m} + a[(d-1) \otimes \dots \otimes (d-1-k_s) \otimes \dots \otimes (d-1) \otimes \dots \otimes (d-1-k_1) \otimes \dots \otimes (d-1)] \\ &= e_{d^m-1} + ae_l \end{aligned}$$

where  $l = d^m - 1 - (k_1 d^{j_1} + \dots + k_s d^{j_s})$ ,  $I_d$  is the  $d$  dimensional identity operator, and we used (1) for the last equality. □

Similarly, we can prove the following lemma.



where

$$\vec{a} = (0, \dots, 0, a), \quad \left[ \begin{array}{c} \text{K}_1 \\ \text{a} \end{array} \right] = a.$$

By the map-state duality, we get the universality of qudit ZX-calculus over  $\mathbb{C}$ : any  $d^m \times d^n$  matrix  $A$  with  $m, n \geq 0$  can be represented by a ZX diagram.

## 5 Qufinite ZX-calculus

Based on the qudit ZX-calculi introduced in previous sections, now we set up a unified framework which we call qufinite ZX-calculus. The main idea is to label each wire with its dimension and add two new generators called dimension-splitter and dimension-binder respectively which were first presented in [16] and then deployed in [13]. Note that a wire labelled with 1 will be depicted as empty, as usually did.

First we give the generators of qufinite ZX-calculus.

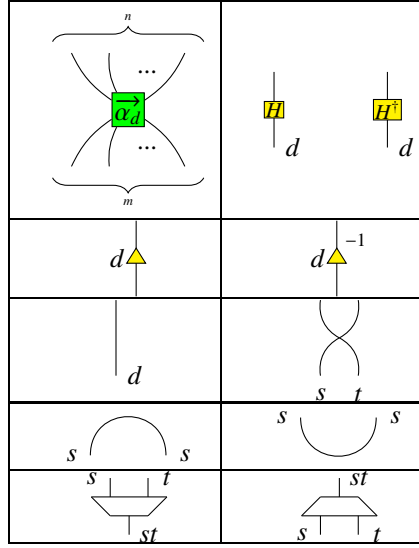


Table 2: Generators of qufinite ZX-calculus, where  $d, m, n \in \mathbb{N}, d \geq 2; \vec{a}_d = (a_1, \dots, a_{d-1}); a_i \in \mathbb{C}; i \in \{1, \dots, d-1\}; j \in \{0, 1, \dots, d-1\}; s, t \in \mathbb{N} \setminus \{0\}$ .

**Remark 5.1** The two diagrams at the bottom of the table of generators are called dimension-binder and dimension-splitter respectively, in the qubit case they are similar to the divider and gatherer in the as introduced in [2].

Since now wires are labelled with any positive integers, the category of diagrams is not a PROP anymore, but still a compact closed category.



The rules of qufinite ZX-calculus can be divided in two parts: one part is the same as the qudit rules except each wire labelled with an integer  $d$ , the other part has dimension-splitter and dimension-binder involved. Below we only give the rules of the second part which were partly shown in [13].

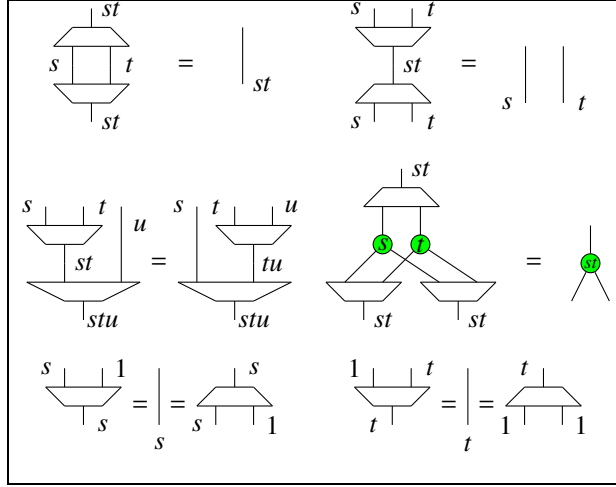


Figure 3: Qufinite ZX-calculus rules II, where  $\vec{1}_d = \overbrace{(1, \dots, 1)}^{d-1}$ ,  $\vec{0}_d = \overbrace{(0, \dots, 0)}^{d-1}$ ,  $\vec{\alpha}_d = (a_1, \dots, a_{d-1})$ ,  $\vec{\beta}_d = (b_1, \dots, b_{d-1})$ ,  $a_k, b_k \in \mathbb{C}$ ,  $k \in \{1, \dots, d-1\}$ ,  $j \in \{1, \dots, d-1\}$ ,  $s, t, u \in \mathbb{N} \setminus \{0\}$ .

$$\left[ \begin{array}{c} s \\ \text{---} \\ \text{---} \\ \text{---} \\ st \end{array} \right] = \sum_{k=0}^{s-1} \sum_{l=0}^{t-1} |kt+l\rangle \langle kl|, \quad \left[ \begin{array}{c} st \\ \text{---} \\ \text{---} \\ s \quad t \end{array} \right] = \sum_{k=0}^{st-1} \left[ \left\lfloor \frac{k}{t} \right\rfloor \right] |k-t \left\lfloor \frac{k}{t} \right\rfloor \rangle \langle k|, \quad \left[ \begin{array}{c} \text{---} \\ \text{---} \\ \text{---} \\ s \quad t \end{array} \right] = \sum_{k=0}^{s-1} \sum_{l=0}^{t-1} |kl\rangle \langle lk|,$$

$$[[D_1 \otimes D_2]] = [[D_1]] \otimes [[D_2]], \quad [[D_1 \circ D_2]] = [[D_1]] \circ [[D_2]],$$

where  $s, t \in \mathbb{N} \setminus \{0\}$ ,  $\langle i| = \overbrace{(0, \dots, 1, \dots, 0)}^d$ ,  $|i\rangle = \overbrace{((0, \dots, 1, \dots, 0))^T}^d$ ,  $i \in \{0, 1, \dots, d-1\}$ , and  $[r]$  is the integer part of a real number  $r$ .

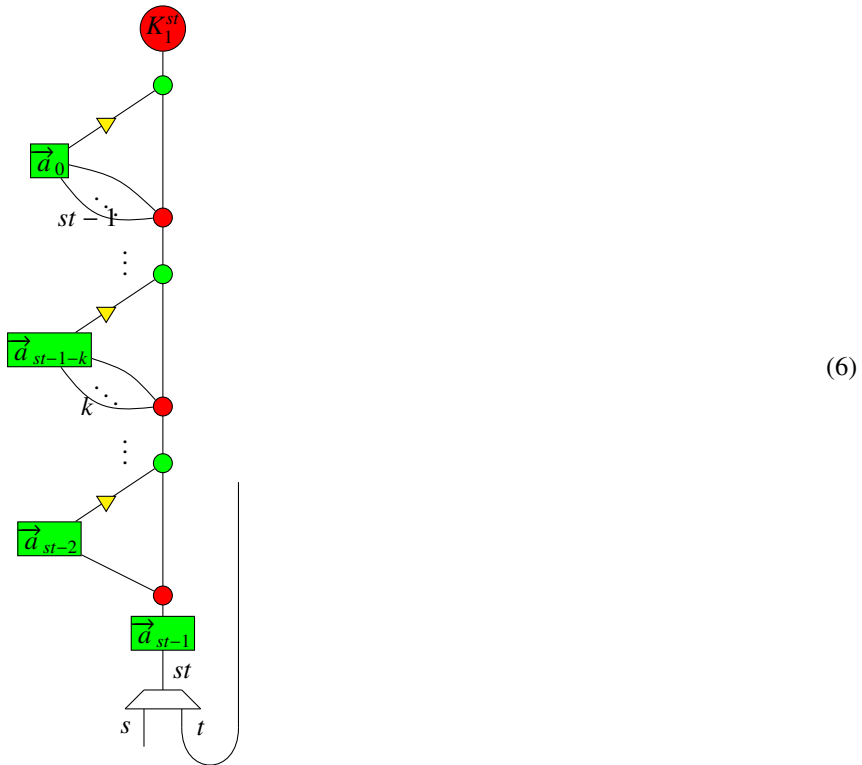
**Remark 5.2** In the 1-dimensional Hilbert space  $H_1 = \mathbb{C}$ , we make the convention that  $|0\rangle = 1$ .

## 5.1 Normal form and universality

Given an arbitrary  $s \times t$  matrix  $M$  over  $\mathbb{C}$ :

$$M = \begin{pmatrix} a_0 & a_1 & \cdots & a_{t-1} \\ a_t & a_{t+1} & \cdots & a_{t+t-1} \\ \vdots & \ddots & & \vdots \\ a_{kt} & a_{kt+1} & \cdots & a_{kt+t-1} \\ \vdots & & \ddots & \vdots \\ a_{(s-1)t} & a_{(s-1)t+1} & \cdots & a_{(s-1)t+t-1} \end{pmatrix} = (a_{kt+l})_{0 \leq k \leq s-1, 0 \leq l \leq t-1} \quad (5)$$

**Theorem 5.3** *The matrix shown in (5) can be represented by the following diagram:*



where  $1 \leq k \leq st-1$ ,  $\vec{a}_i = \overbrace{(0, \dots, 0, a_i)}^{st-1}$ ,  $0 \leq i \leq st-2$ ,  $\vec{a}_{st-1} = \overbrace{(1, \dots, 1, a_{st-1})}^{st-1}$ .

**Proof:** By the normal form for qudits, the diagram excluding the dimension-splitter

represents the following vector

$$\begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_{st-2} \\ a_{st-1} \end{pmatrix} = \sum_{i=0}^{st-1} a_i |i\rangle$$

Then the whole diagram (6) represents

$$(I_s \otimes \sum_{i=0}^{t-1} \langle i | \langle i |) \left( \sum_{k=0}^{st-1} |[\frac{k}{t}] \rangle |k - t[\frac{k}{t}] \rangle \langle k | \otimes I_t \right) \left( \sum_{i=0}^{st-1} a_i |i \rangle \otimes I_t \right)$$

Then in matrix form, its element in  $v$ -th row and the  $l$ -th column ( $0 \leq v \leq s-1, 0 \leq l \leq t-1$ ) is

$$\begin{aligned} & \langle v | (I_s \otimes \sum_{i=0}^{t-1} \langle i | \langle i |) \left( \sum_{k=0}^{st-1} |[\frac{k}{t}] \rangle |k - t[\frac{k}{t}] \rangle \langle k | \otimes I_t \right) \left( \sum_{i=0}^{st-1} a_i |i \rangle \otimes I_t \right) | l \rangle \\ &= \langle v | (I_s \otimes \sum_{i=0}^{t-1} \langle i | \langle i |) \left( \sum_{k=0}^{st-1} a_k |[\frac{k}{t}] \rangle |k - t[\frac{k}{t}] \rangle \right) | l \rangle \\ &= \langle v | \sum_{k-t[\frac{k}{t}]=l} a_k |[\frac{k}{t}] \rangle \\ &= \sum_{k-t[\frac{k}{t}]=l, v=[\frac{k}{t}]} a_k \langle v | |[\frac{k}{t}] \rangle = a_{t+vt} \end{aligned}$$

□

**Remark 5.4** Given matrix (5), the diagram of form (6) is unique, thus will be called a norm form of qfinite ZX-calculus. This representation actually works for matrices over arbitrary commutative semirings as well.

Another interesting observation is that the requirement of  $t = u$  when defining multiplication of matrices  $M_{s \times t} N_{u \times v}$  can now be clearly seen as the need of type matching for composing the normal form (6).

## 6 Conclusion and further work

In this paper, we generalise the qubit ZX-calculus to qudit ZX-calculus in any finite dimension by introducing Z spider with complex-number phase vector and generalised triangle node as new generators. As a consequence, we obtained qudit rewriting rules which can be seen as direct generalisation of qubit rules. Furthermore, we construct a normal form for any qudit vectors, which exhibits universality for qudit ZX-calculus. Finally, we propose qfinite ZX-calculus as a unified framework for qudit ZX-calculi in all finite dimensions, with a normal form for matrix of any finite size.

The next work would naturally be to prove the completeness of qudit ZX-calculus and qfinite ZX-calculus, over complex numbers and arbitrary commutative semirings

respectively, following the method used in [14, 15]. Another interesting work would be to give a fine-grained version of the diagrammatic reconstruction of finite quantum theory [12] within the framework of qfinite ZX-calculus.

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